

W. Utschick · H. Boche · R. Mathar

Series Editors

FOUNDATIONS IN SIGNAL PROCESSING,
COMMUNICATION AND NETWORKING

VOLUME 1

Linear Estimation and Detection in Krylov Subspaces

Guido K.E. Dietl *Editor*



Springer

Foundations in Signal Processing, Communications and Networking

Series Editors: W. Utschick, H. Boche, R. Mathar

Foundations in Signal Processing, Communications and Networking

Series Editors: W. Utschick, H. Boche, R. Mathar

Vol.1. Dietl, G. K. E.

Linear Estimation and Detection in Krylov Subspaces, 2007

ISBN 978-3-540-68478-7

Guido K. E. Dietl

Linear Estimation and Detection in Krylov Subspaces

With 53 Figures and 11 Tables

 Springer

Series Editors:

Wolfgang Utschick
TU Munich
Institute for Circuit Theory
and Signal Processing
Arcisstrasse 21
80290 Munich, Germany

Holger Boche
TU Berlin
Dept. of Telecommunication Systems
Heinrich-Hertz-Chair for Mobile
Communications
Einsteinufer 25
10587 Berlin, Germany

Rudolf Mathar
RWTH Aachen University
Institute of Theoretical
Information Technology
52056 Aachen, Germany

Author:

Guido Dietl
Munich, Germany
guido.dietl@mytum.de

ISSN print edition: 1863-8538

ISBN 978-3-540-68478-7 Springer Berlin Heidelberg New York

Library of Congress Control Number: 2007928954

This work is subject to copyright. All rights are reserved, whether the whole or part of the material is concerned, specifically the rights of translation, reprinting, reuse of illustrations, recitation, broadcasting, reproduction on microfilm or in any other way, and storage in data banks. Duplication of this publication or parts thereof is permitted only under the provisions of the German Copyright Law of September 9, 1965, in its current version, and permission for use must always be obtained from Springer. Violations are liable for prosecution under the German Copyright Law.

Springer is a part of Springer Science+Business Media

springer.com

© Springer-Verlag Berlin Heidelberg 2007

The use of general descriptive names, registered names, trademarks, etc. in this publication does not imply, even in the absence of a specific statement, that such names are exempt from the relevant protective laws and regulations and therefore free for general use.

Typesetting: by the author and Integra using Springer L^AT_EX package
Cover Design: deblik, Berlin

Printed on acid-free paper SPIN: 11936770 42/3100/Integra 5 4 3 2 1 0

To Anja

Preface

One major area in the theory of statistical signal processing is reduced-rank estimation where optimal linear estimators are approximated in low-dimensional subspaces, e. g., in order to reduce the noise in overmodeled problems, enhance the performance in case of estimated statistics, and/or save computational complexity in the design of the estimator which requires the solution of linear equation systems. This book provides a comprehensive overview over reduced-rank filters where the main emphasis is put on matrix-valued filters whose design requires the solution of linear systems with multiple right-hand sides. In particular, the multistage matrix Wiener filter, i. e., a reduced-rank Wiener filter based on the multistage decomposition, is derived in its most general form.

In numerical mathematics, iterative block Krylov methods are very popular techniques for solving systems of linear equations with multiple right-hand sides, especially if the systems are large and sparse. Besides presenting a detailed overview of the most important block Krylov methods in Chapter 3, which may also serve as an introduction to the topic, their connection to the multistage matrix Wiener filter is revealed in this book. Especially, the reader will learn the restrictions of the multistage matrix Wiener filter which are necessary in order to end up in a block Krylov method. This relationship is of great theoretical importance because it connects two different fields of mathematics, viz., statistical signal processing and numerical linear algebra.

This book mainly addresses readers who are interested in the theory of reduced-rank signal processing and block Krylov methods. However, it includes also practical issues like efficient algorithms for direct implementation or the exact computational complexity in terms of the required number of floating point operations. If the reader is not interested in these practical aspects, Sections 2.2, 4.3, and 4.4 of this book can be skipped.

Finally, the book covers additionally the application of the proposed linear estimators to a detection problem occurring at the receiver of a digital communication system. An iterative (Turbo) multiuser detector is considered where users are separated via spread spectrum techniques. Besides using

Monte Carlo simulations, the communication system is investigated in terms of the expected iterative estimation error based on extrinsic information transfer charts. It should be mentioned that the extrinsic information transfer characteristics that are shown in these charts, are calculated in a semianalytical way as derived in Section 6.1.2.

This text has been written at the Associate Institute for Signal Processing, Munich University of Technology, Germany, where I was working as a research engineer towards my doctoral degree. I would like to express my deep gratitude to Prof. Wolfgang Utschick who supervised me at the institute. I appreciate his helpful advice and steady support, as well as the numerous discussions which had a great impact on this book. Besides, I thank Prof. Michael L. Honig of the Northwestern University, USA, and Prof. Joachim Hagenauer of the Institute for Communications Engineering, Munich University of Technology, both members of my dissertation committee, for reviewing this manuscript. I also thank Prof. Michael D. Zoltowski of Purdue University, USA, for giving me the opportunity to stay at Purdue University in winter 2000/2001 and summer 2004. In fact, he initiated my research on the multistage Wiener filter and Krylov methods. Further, I would like to thank Prof. Josef A. Nossek of the Institute for Circuit Theory and Signal Processing, Munich University of Technology, for his support.

Finally, many thanks to all the excellent students which I had the chance to supervise at the Munich University of Technology. Their research results deeply influenced this book. Moreover, I thank all my colleagues at the institute for the nice atmosphere and the inspiring discussions.

Munich, March 2007

Guido Diethl

Contents

1	Introduction	1
1.1	Overview and Contributions	4
1.2	Notation	7

Part I Theory: Linear Estimation in Krylov Subspaces

2	Efficient Matrix Wiener Filter Implementations	13
2.1	Matrix Wiener Filter (MWF)	14
2.2	Reduced-Complexity MWFs	17
2.2.1	Implementation Based on Cholesky Factorization	18
2.2.2	Exploitation of Structured Time-Dependency	22
2.3	Reduced-Rank MWFs	26
2.3.1	Principal Component (PC) Method	29
2.3.2	Cross-Spectral (CS) Method	30
3	Block Krylov Methods	33
3.1	Principles and Application Areas	35
3.2	Block Arnoldi Algorithm	38
3.3	Block Lanczos Algorithm	41
3.3.1	Original Version	41
3.3.2	Dimension-Flexible Ruhe Version	43
3.4	Block Conjugate Gradient (BCG) Algorithm	46
3.4.1	Original Version	46
3.4.2	Rate of Convergence	54
3.4.3	Regularizing Effect	60
3.4.4	Dimension-Flexible Version	66
4	Reduced-Rank Matrix Wiener Filters in Krylov Subspaces	71
4.1	MultiStage Matrix Wiener Filter (MSMWF)	73
4.1.1	Multistage Decomposition	73

4.1.2	Reduced-Rank MSMWF	81
4.1.3	Fundamental Properties	85
4.2	Relationship Between MSMWF and Krylov Subspace Methods	91
4.2.1	Relationship to Krylov Subspace	91
4.2.2	Block Arnoldi–Lanczos Connection	95
4.2.3	BCG Connection	97
4.3	Krylov Subspace Based MSMWF Implementations	98
4.3.1	Block Lanczos–Ruhe (BLR) Implementation	98
4.3.2	BCG Implementation	103
4.4	Computational Complexity Considerations	103

Part II Application: Iterative Multiuser Detection

5	System Model for Iterative Multiuser Detection	113
5.1	Transmitter Structure	115
5.1.1	Channel Coding	115
5.1.2	Interleaving	118
5.1.3	Symbol Mapping	119
5.1.4	Spreading	121
5.2	Channel Model	124
5.3	Iterative Receiver Structure	126
5.3.1	A Priori Based Linear Equalization	128
5.3.2	Soft Symbol Demapping	134
5.3.3	Decoding	137
5.3.4	Relationship to Iterative Soft Interference Cancellation ..	138
6	System Performance	141
6.1	EXtrinsic Information Transfer (EXIT) Charts	142
6.1.1	Principles	142
6.1.2	Semianalytical Calculation of EXIT Characteristics for Linear Equalizers	146
6.2	Analysis Based on EXIT Charts	152
6.2.1	EXIT Characteristics Analysis for Single-User System with Fixed Channels	152
6.2.2	Mean Square Error (MSE) Analysis for Single-User System with Fixed Channels	156
6.2.3	MSE Analysis for Multiuser System with Random Channels	158
6.2.4	Complexity Analysis – Rank Versus Order Reduction ..	162
6.3	Bit Error Rate (BER) Performance Analysis	165
7	Conclusions	175

A Mathematical Basics 177

 A.1 Inverses of Structured Matrices 177

 A.1.1 Inverse of a Schur Complement 177

 A.1.2 Inverse of a Partitioned Matrix 177

 A.2 Matrix Norms 178

 A.2.1 Hilbert–Schmidt or Frobenius norm 178

 A.2.2 A-norm 179

 A.2.3 2-norm 179

 A.3 Chebyshev Polynomials 179

 A.4 Regularization 180

 A.5 Vector Valued Function of a Matrix and Kronecker Product . . . 183

 A.6 Square Root Matrices 184

 A.7 Binary Galois Field 185

B Derivations and Proofs 187

 B.1 Inversion of Hermitian and Positive Definite Matrices 187

 B.2 Real-Valued Coefficients of Krylov Subspace Polynomials 190

 B.3 QR Factorization 191

 B.4 Proof of Proposition 3.3 192

 B.5 Correlated Subspace 195

C Abbreviations and Acronyms 201

References 205

Index 223

List of Algorithms

2.1. Cholesky Factorization (CF)	20
2.2. Forward Substitution (FS)	21
2.3. Backward Substitution (BS)	22
2.4. Reduced-Complexity (RC) MWF exploiting time-dependency ..	25
3.1. Block Arnoldi	40
3.2. Block Lanczos	43
3.3. Block Lanczos–Ruhe	45
3.4. Block Conjugate Gradient (BCG)	54
3.5. Dimension-flexible version of the BCG procedure	69
4.1. Rank D MultiStage Matrix Wiener Filter (MSMWF)	83
4.2. Block Lanczos–Ruhe (BLR) implementation of the MSMWF ...	104
4.3. BCG implementation of the MSMWF	105
B.1. Lower Triangular Inversion (LTI)	188
B.2. Lower Triangular Product (LTP)	189
B.3. QR factorization	192

List of Figures

2.1	Matrix Wiener Filter (MWF)	16
2.2	Structure of the auto-covariance matrix $\mathbf{C}_y[i]$ for $i \in \{n-1, n\}$.	23
2.3	Reduced-rank MWF	27
3.1	Structure of the $D \times D$ band Hessenberg matrix \mathbf{H} with M subdiagonals	41
3.2	Structure of the Hermitian $D \times D$ band Hessenberg matrix \mathbf{H} with bandwidth $2M + 1$	42
3.3	Polynomial approximation $\bar{P}^{(\ell+1)}(\lambda)$ of degree $\ell \in \{1, 2, 7\}$	58
3.4	Filter factors of the CG algorithm	65
3.5	Filter factors of the BCG algorithm ($j = 1$)	67
4.1	Matrix Wiener Filter (MWF) with full-rank prefilter	74
4.2	Decomposition of the MWF $\mathbf{W}[n]$	77
4.3	Simplified decomposition of the MWF $\mathbf{W}[n]$	78
4.4	Decomposition of the MWF $\mathbf{G}_{\ell-1}[n]$	78
4.5	Decomposition of the MWF $\mathbf{G}_{L-2}[n]$	80
4.6	Full-rank MultiStage Matrix Wiener Filter (MSMWF)	81
4.7	Rank D MSMWF	81
4.8	Rank D MSMWF as a filter bank	84
4.9	Structure of a block tridiagonal $D \times D$ matrix with $M \times M$ blocks	87
4.10	MSMWF performance for different blocking matrices	90
4.11	Submatrices $\mathbf{D}_{\leftarrow M}^{(j)} \in \mathbb{C}^{j \times M}$, $\mathbf{D}_{\rightarrow M}^{(j)} \in \mathbb{C}^{j \times M}$, and $\mathbf{D}_{\rightarrow M-1}^{(j)} \in \mathbb{C}^{j \times (M-1)}$ of the matrices $\mathbf{D}^{(j)}$ and $\mathbf{D}_{\rightarrow M}^{(j)}$, respectively, $j \in \{M, M+1, \dots, D\}$	101
4.12	Computational complexity versus N of different MWF implementations ($M = 4, S = 512$)	108
4.13	Computational complexity versus D of different MWF implementations ($N = 50, S = 512$)	109

4.14	Computational complexity versus M of different MWF implementations ($N = 50, S = 512$)	109
5.1	Transmitter structure of user k for a coded DS-CDMA system	115
5.2	Rate $r = 1/p$ feedforward convolutional encoder with generator sequence $\mathbf{p}[n]$	116
5.3	(7,5)-convolutional encoder with rate $r = 1/2$ and memory $m = 2$	118
5.4	QPSK symbols with $\varrho_s = 1$	120
5.5	Orthogonal Variable Spreading Factor (OVSF) code tree	122
5.6	Spreading for DS-CDMA	123
5.7	Time-dispersive Multiple-Access (MA) Single-Input Multiple-Output (SIMO) channel	124
5.8	Iterative multiuser receiver for a coded DS-CDMA system	127
5.9	A priori based linear multiuser equalizer	128
5.10	Soft symbol demapper for user k	134
5.11	Alternative representation of linear multiuser equalizer	138
6.1	EXIT chart example for single-user system with one receive antenna ($K = R = \chi = 1, F = 7$) at $10 \log_{10}(E_b/N_0) = 5$ dB	145
6.2	Statistical model of linear equalizer and soft symbol demapper of user k	147
6.3	Quality of semianalytical calculation of equalizer-demapper EXIT characteristics for single-user system with Proakis b channel ($K = R = \chi = 1, F = 7$) and multiuser system with random channel ($K = \chi = 4, R = 2, F = 25$) at $10 \log_{10}(E_b/N_0) = 5$ dB	152
6.4	EXIT characteristics of different time-variant equalizers in a single-user system with Proakis b channel ($K = R = \chi = 1, F = 7$) at $10 \log_{10}(E_b/N_0) = 5$ dB	154
6.5	EXIT characteristics of different time-variant equalizers in a single-user system with Proakis c channel ($K = R = \chi = 1, F = 7$) at $10 \log_{10}(E_b/N_0) = 5$ dB	155
6.6	EXIT characteristics of different time-variant equalizers in a single-user system with Porat channel ($K = R = \chi = 1, F = 7$) at $10 \log_{10}(E_b/N_0) = 5$ dB	155
6.7	Mutual Information (MI) and Mean Square Error (MSE) performance of different equalizers in a single-user system with Proakis b channel ($K = R = \chi = 1, F = 7, \text{Turbo iteration } \infty$)	157
6.8	MSE performance of different equalizers in a single-user system with Proakis c channel ($K = R = \chi = 1, F = 7, \text{Turbo iteration } \infty$)	158
6.9	MSE performance of different equalizers in a single-user system with Porat channel ($K = R = \chi = 1, F = 7, \text{Turbo iteration } \infty$)	159

6.10	MSE performance of different equalizers in a multiuser system with random channel of an exponential power delay profile ($K = \chi = 4, R = 2, F = 25$)	161
6.11	MSE performance of different equalizers in a multiuser system with random channel of an exponential power delay profile ($K = \chi = 4, R = 2, F = 25$, Turbo iteration ∞)	162
6.12	Complexity–performance chart for single-user system with a random channel of a uniform power delay profile ($K = R = \chi = 1, F = N$) at $10 \log_{10}(E_b/N_0) = 5$ dB assuming perfect Channel State Information (CSI)	164
6.13	Complexity–performance chart for single-user system with a random channel of a uniform power delay profile ($K = R = \chi = 1, F = N$) at $10 \log_{10}(E_b/N_0) = 5$ dB assuming estimated CSI (Turbo iteration 0)	165
6.14	BER performance of time-invariant and Time-Variant (TV) equalizers in a multiuser system with random channel of an exponential power delay profile ($K = \chi = 4, R = 2, F = 25$) . . .	167
6.15	BER performance of the dimension-flexible BCG in a multiuser system with random channel of an exponential power delay profile ($K = \chi = 4, R = 2, F = 25$)	169
6.16	BER performance of vector and matrix equalizers in a multiuser system with random channel of an exponential power delay profile ($K = \chi = 4, R = 2, F = 25$)	170
6.17	BER performance of different equalizers in a multiuser system with random channel of an exponential power delay profile ($K = \chi = 4, R = 2, F = 25$) assuming perfect or estimated CSI (15 pilot symbols)	172
6.18	BER performance of different equalizers in a multiuser system with random channel of an exponential power delay profile ($K = \chi = 4, R = 2, F = 25$) assuming estimated CSI (5 pilot symbols)	173
A.1	Chebyshev polynomials $T^{(n)}(x)$ of the first kind and degree $n \in \{2, 3, 8\}$	181
B.1	Graphs of functions $\iota(j)$, i. e., one plus the maximal polynomial degree, and the number $\varrho(j)$ of polynomials with maximal degree $\iota(j) - 1$	196